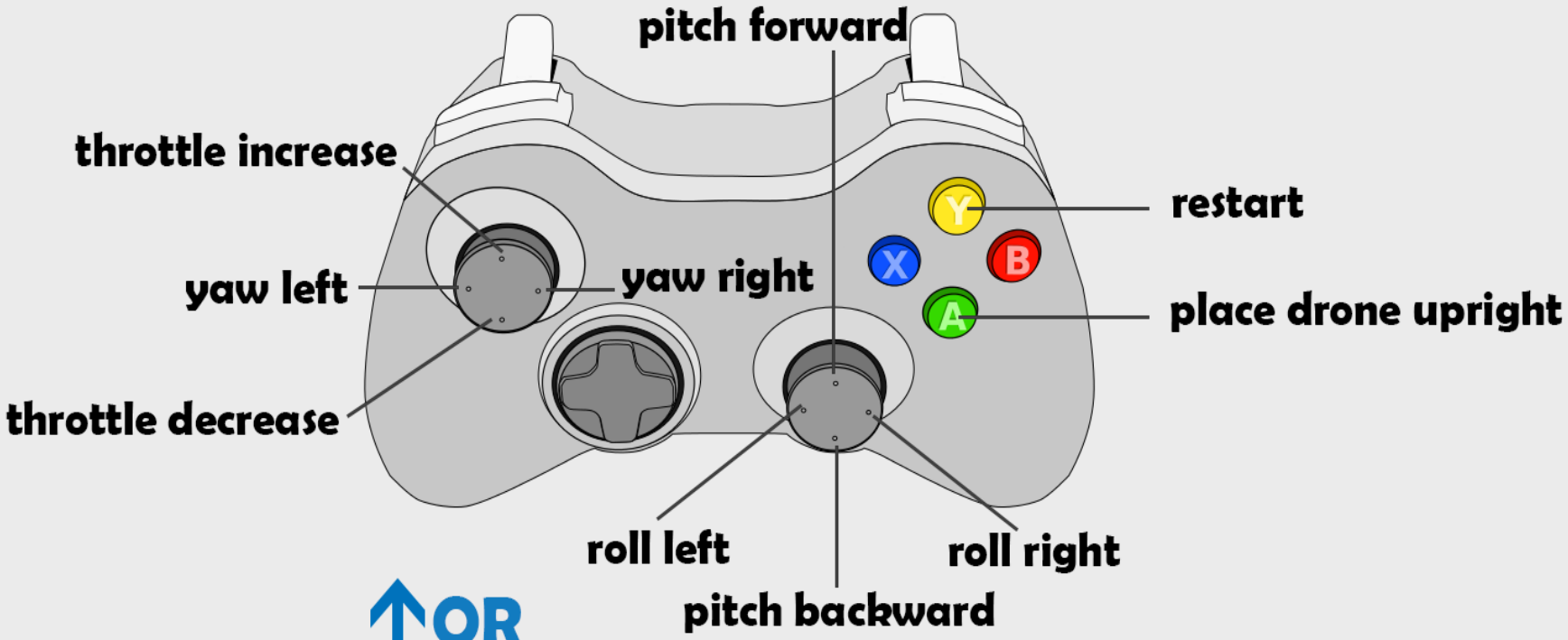
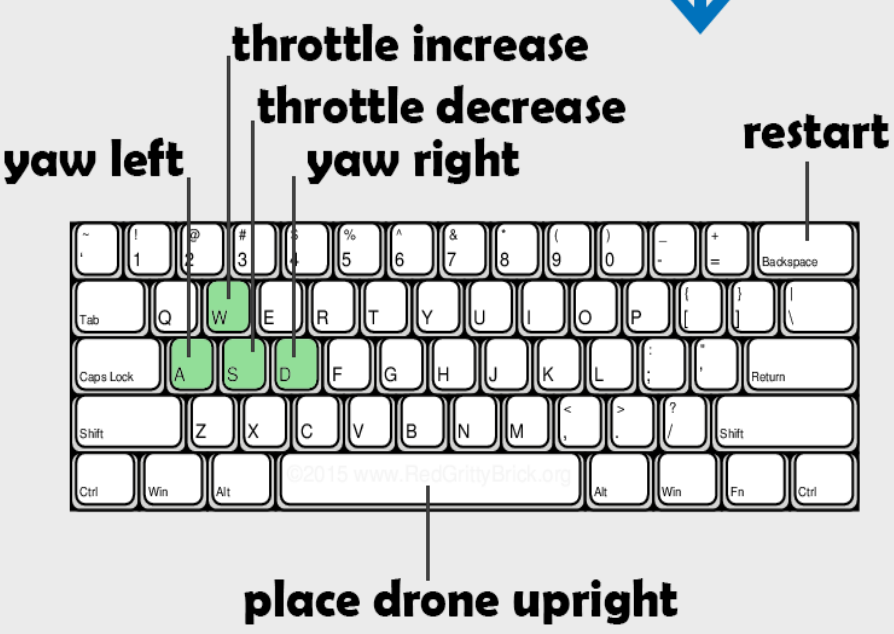
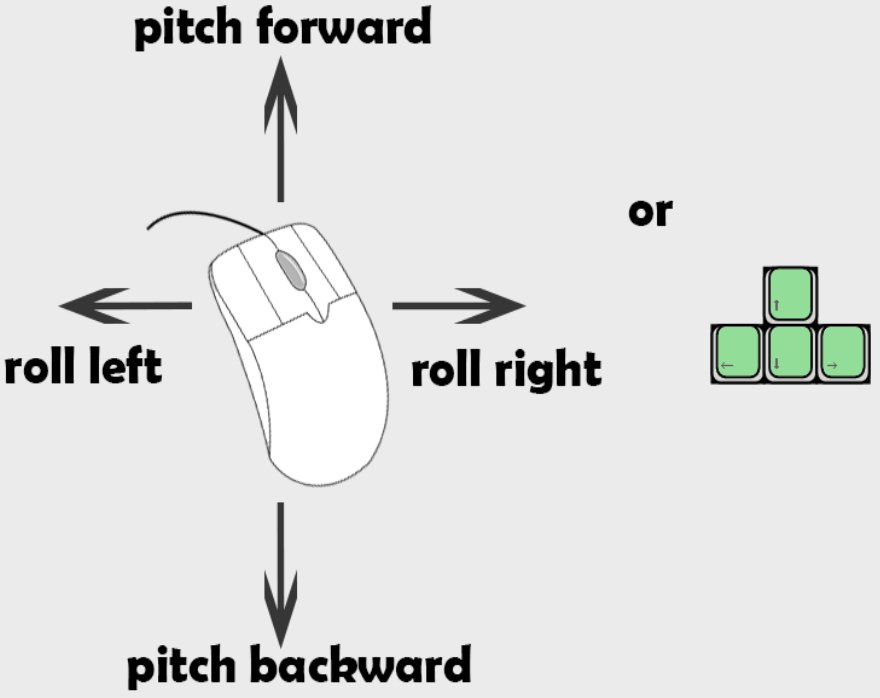

pitch forward
throttle increase
restart
yaw left
yaw right
place drone upright
throttle decrease
roll left
roll right
pitch backward

OR


throttle increase
throttle decrease
yaw left
yaw right
restart
place drone upright


pitch forward
or
roll left
roll right
pitch backward